## FTR - Flight Test Report

Dieser Prüfbericht darf ohne schriftliche Zustimmung der EAPR nicht, auch nicht auszugsweise, vervielfältigt werden

Manufacturer	CARD ************************************	Type testing No.	EAPR-GS-0336/15	
	ICARO Paragliders Hochrießstraße 1 D-8316 Flintsbach	serial number	010aqlf120	
Model	SITTA 20	Location	Walensee	
		Location	Schruns	



Rev. 2.2 - 09.10.2014 EAPR GmbH - Marktstr. 11 D-87730 Bad Grönenbach - Germany

Date of testing	1314.11.2014	Minimum take o 75 kg	off weight	Maximum take off weight 95 kg			
Testpilot		Mike Küng		Hannes Tschofen			
Harness		Eapr-Test Equipment		EAPR-Testequipment			
Pilot's take off weig	ht	75	kg American	95 k	g A		





Test-criteria		Minimum take off weight	Evaluation	Maximum take off weight	Evaluation			
1. Inflation / take-off - 4.4.1								
Rising behavior		Easy rising, some pilot correction is required	В	Easy rising, some pilot correction is required	В			
Special take off technique required		No	А	No	А			
2. Landing - 4.4.2		1 -						
Special landing technique required		No	А	No	Α			
3. Speeds in straight flight - 4.4.3		-						
Trim speed more than 30km/h		Yes	Α	Yes	А			
Speed range using the controls larger than 10km/h		Yes	Α	Yes	Α			
Minimum speed		Less than 25 km/h	Α	25 km/h to 30 km/h	В			
4. Control movement - 4.4.4								
				I				
Max. weight in flight up to 80kg			-		-			
Max. weight in flight 80 to 100kg		Increasing > 60cm	Α	Increasing 45cm - 60cm	С			
Max. weight in flight greater than 100kg			-		-			
5. Pitch stability exiting accelerated flight - 4.	1.5							
Dive forward angle on exit		Dive forward less than 30°	A	Dive forward less than 30°	A			
Collapse occurs		No	Α	No	Α			
6. Pitch stability operating controls during acc	elerated 1	•		I				
Collapse occurs		No	Α	No	Α			
7. Roll stability and damping - 4.4.7				1				
Oscillations		Reducing	Α	Reducing	Α			
8. Stability in gentle spirals - 4.4.8					l A			
Tendency to return to straight flight		Spontaneous exit	Α	Spontaneous exit				
9. Behaviour exiting a fully developed spiral d	ive - 4.4.9							
Initial response of glider (first 180°)		No immediate reaction	В	No immediate reaction	B D			
Tendency to return to straight flight Turn angle to recover normal flight		Spontaneous exit 720° to 1080°, spontaneous recovery	A B	Turn remains constant With pilot action				
10. Symmetric front collapse - 4.4.10		720 to 1000 , spontaneous recovery	Б	With piot dotton	D			
Folding lines used		I No		I No				
Entry	.,	Rocking back less than 45°	А	Rocking back less than 45°	Α			
•	%0°.~	· · ·	В		В			
Recovery	pee	Spontaneous in 3 to 5 sec		Spontaneous in 3 to 5 sec				
Dive forward angle on exit	rim speed	30° - 60° Entering a turn of less than 90		30° - 60° Keeping course	В			
Cascade occurs Entry		No Rocking back less than 45°	A	No Rocking back less than 45°	A			
Recovery	- 20% p < p	Spontaneous in 3 to 5 sec	В	Spontaneous in 3 to 5 sec	В			
Dive forward angle on exit	trim speed	30° - 60° Entering a turn of less than 90	)° B	30° - 60° Keeping course	В			
Cascade occurs	ţ	No	A	No	A			
Entry	50%	Rocking back less than 45°	А	Rocking back less than 45°	A			
Recovery	accelerated > 5	Spontaneous in 3 to 5 sec	В	Spontaneous in 3 to 5 sec	В			
Dive forward angle on exit	coelen	30° - 60° Entering a turn of less than 90		30° - 60° Entering a turn of less than 90°	В			
Cascade occurs		No	А	No	Α			
11. Exiting deep stall (parachutal stall) - 4.4.1	1							
Deep stall achieved		Yes		Yes				
Recovery		Spontaneous in less than 3 sec	Α	Spontaneous in less than 3 sec				
Dive forward angle on exit			В	30° - 60°				
Change of course		Changing course less than 45°	A	Changing course less than 45°	A			
Cascade occurs		No	Α	No				

12. High angle of attack recovery - 4.4.12									
Recovery		Spontaneous in less than 3 sec		А	Spontaneous in 3 to 5 sec			С	
Cascade occurs		No		A	No			A	
13. Recovery from a developed full stall - 4.4.13		140							
Dive forward angle on exit		30° - 60°			В	30° - 60°			В
Collapse Cascade occurs (other than collapse)		No collapse No			A	No collapse No			A
Rocking backward		Less than 45°			Α	Less than 45°			Α
Line tension		Most lines tight			А	Most lines tight			А
14. Asymmetric collapse (trim speed) - 4.4.14 Folding lines used		No				No			
Change of course until re-inflation		90° - 180°	Dive or roll angle	15° - 45°	В	< 90°	Dive or roll angle	15° - 45°	А
	trim speed, max 50% collapse								
Re-inflation behavior	trim speed, x 50% colla	Spontaneous re-inflation		А	Spontaneous re-inflation  Less than 360°  No  No			А	
Total change of course  Collapse on the opposite side occurs	trim s c 50%	Less than 360° No		A				A	
Twist occurs	ma .	No		A				Α	
Cascade occurs		No	1	1	A	No			A
Change of course until re-inflation	esc	90° - 180°	Dive or roll angle	15° - 45°	В	90° - 180°	Dive or roll angle	45° - 60°	С
Re-inflation behavior	trim speed, max 75% collapse	Spontaneous re-	-inflation		Α	Spontaneous re	e-inflation		А
Total change of course	trim speed, x 75% colla	Less than 360°		A	Less than 360°		A		
Collapse on the opposite side occurs	trin ax 7	No			Α	No			Α
Twist occurs Cascade occurs	Ε	No No		A	No No			A	
		ı	1	I			1		
Change of course until re-inflation	Se	90° - 180°	Dive or roll angle	15° - 45°	В	90° - 180°	Dive or roll angle	15° - 45°	В
Re-inflation behavior	accelerated, max 50% collapse	Spontaneous re-	-inflation	<u>-</u>	А	Spontaneous re	e-inflation		Α
Total change of course	accelerated, x 50% collap	Less than 360°			Α	Less than 360°			А
Collapse on the opposite side occurs	acc ax 5	No			Α	No			А
Twist occurs Cascade occurs	Ë	No No			A	No No			A
Change of course until re-inflation		90° - 180°	Dive or roll angle	45° - 60°	C	90° - 180°	Dive or roll angle	45° - 60°	C
oriange or course until te illimation	apse	30 100	Dire or for ange	40 00	0	30 100	Dive or rost unge	40 00	
Re-inflation behavior	accelerated, max 75% collapse	Spontaneous re-	-inflation		Α	Spontaneous re	e-inflation		Α
Total change of course	xele 75%	Less than 360°			A	Less than 360°			A
Collapse on the opposite side occurs Twist occurs	ac	No No		A	No No			A	
Cascade occurs	ı	No			A	No No			A
15. Directional control with a maintained asymm	metric col	lapse - 4.4.15							
Able to keep course straight		Yes			Α	Yes			Α
180° turn away from the collapsed side possible in	10 sec	Yes			Α	Yes	Α		
Amount of control range between turn and stall or spin		More than 50% of the symmetric control travel		А	More than 50% of the symmetric control travel			А	
16. Trim speed spin tendency - 4.4.16	<u> </u>								
Spin occurs		No			A	No			Α
17. Low speed spin tendency - 4.4.17		140			, ,,				
Spin occurs		No			Α	No			Α
18. Recovery from a developed spin - 4.4.18									
Spin rotation angle after release		Stops spinning in less than 90°		Α	Stops spinning in 90° to 180°			С	
Cascade occurs		No		А	No			А	
19. B-line-stall - 4.4.19									
Change of course before release		Changing course less than 45°		А	Changing course less than 45°			Α	
Behaviour before release		Remains stable with straight span		Α	Remains stable with straight span			Α	
Recovery		Spontaneous in less than 3 sec		А	Spontaneous in less than 3 sec			А	
Dive forward angle on exit		Spontaneous in less than 3 sec		A	30° - 60°		A		
Cascade occurs		No		A	No			A	
20. Big ears - 4.4.20									
Entry procedure		Standard technique		Α	Special device required			Α	
Behaviour during big ears		Stable flight		Α	Unstable flight		С		
Recovery		Spontaneous in less than 3 sec		А	Spontaneous in 3 to 5 sec			В	
Dive forward angle on exit		0° - 30°		A				A	
21. Big Ears in accelerated flight - 4.4.21									
Entry procedure		Standard technique		А	A Special device required			А	
Behaviour during big ears		Stable flight		A	Stable flight			A	
		Spontaneous in less than 3 sec		A	Spontaneous in 3 to 5 sec			A	
Recovery		Spontaneous in less than 3 sec			·				
Dive forward angle on exit  Behaviour immediately after releasing the accelarator while				A	0° bis 30°			A	
maintaining big ears		Stable flight		А	Unstable flight			С	
23. Alternative means of directional control - 4	1.4.22	1							
180° turn achievable in 20 sec		Yes			Α	Yes			А
Stall or spin occurs		No			Α	No			А
23. Any other flight procedure and/or configura	ation desc	cribed in the user	's manual - 4.4.	23					
Procedure works as descibed					NA NA				NA NA
Procedure suitable for novice pilots  Cascade occurs	+		NA NA				NA NA		
24. Remarks of testpilot:									
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Flight Test Report - Musterprüfnummer: EAPR-GS-0336/15 Seite 2 von 2